

Sparse and Low-Rank: Resource-Efficient Methods in Machine Learning

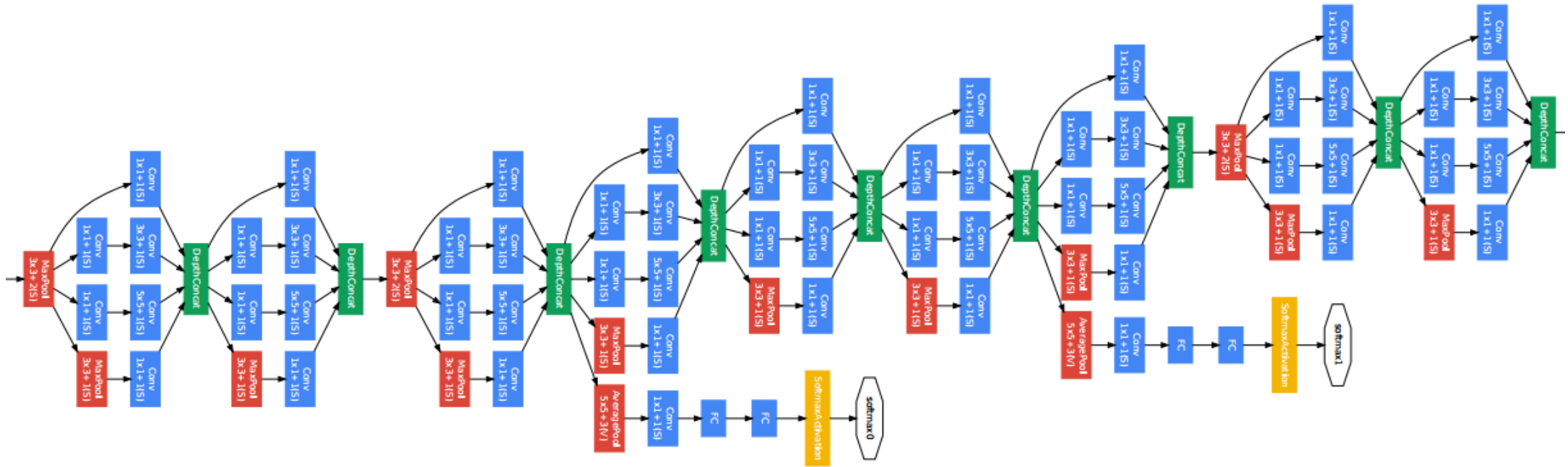
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January 11, 2022

Resource-Efficient Machine Learning

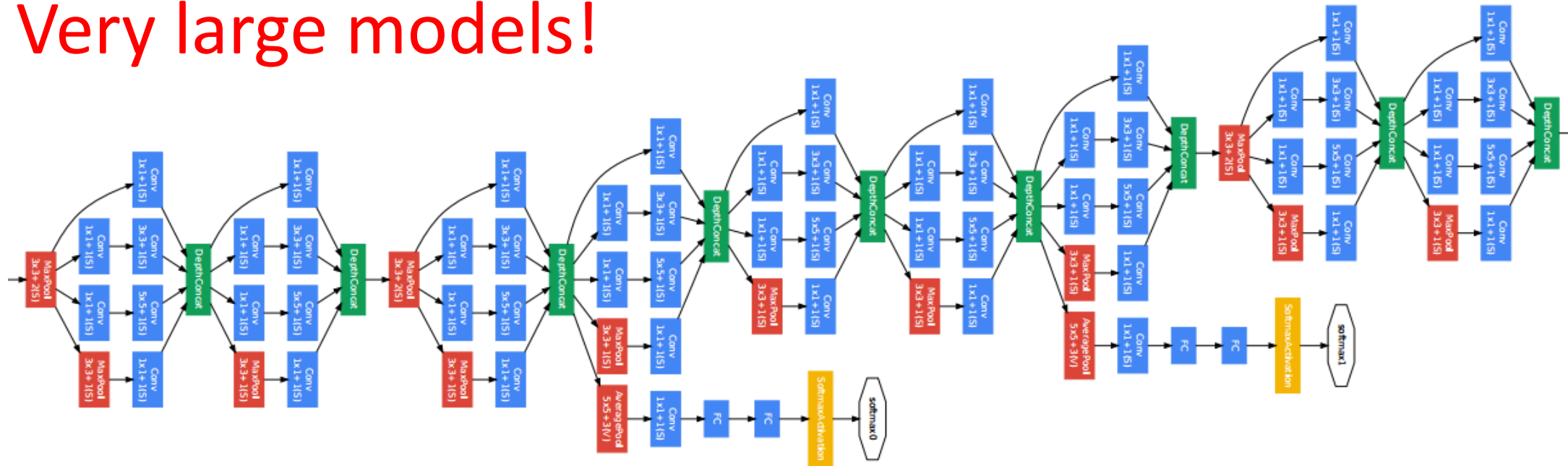
A challenge in modern machine learning:



Resource-Efficient Machine Learning

A challenge in modern machine learning:

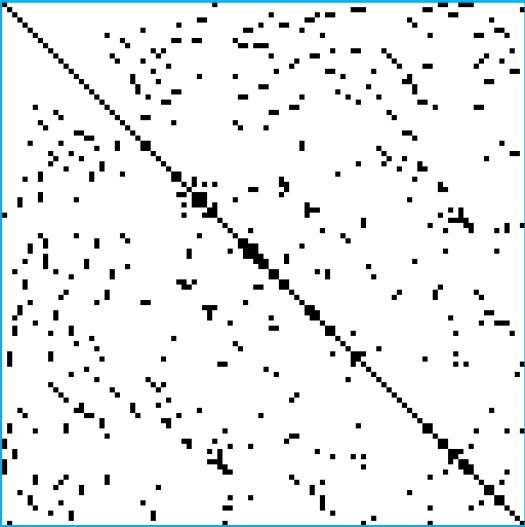
Very large models!



Resource-Efficient Machine Learning

Can we mitigate computational/statistical strains of large nonlinear models via

Sparse models?:

$$\sigma \left(\begin{array}{c} \text{[Sparse Matrix]} \end{array} x \right)$$


Resource-Efficient Machine Learning

Can we mitigate computational/statistical strains of large nonlinear models via

Low-rank models?:

$$\sigma \left(\begin{array}{c} r \\ d \end{array} \times r \begin{array}{c} d \end{array} x \right)$$

Outline of the Talk

1. **Sparse** machine learning for monomials
2. **Low rank** deep learning
3. Future research plans

Sparse Machine Learning

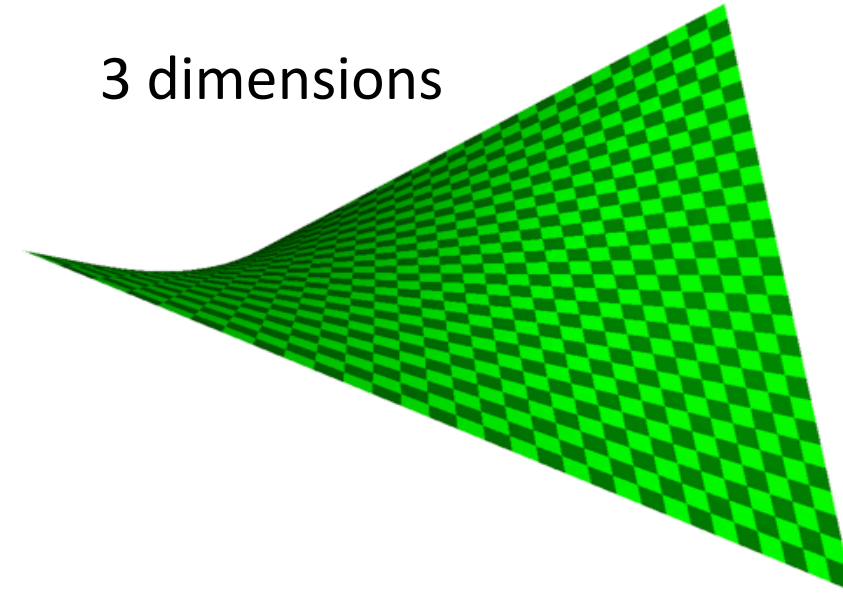
(Attribute-Efficient Learning of Monomials over Highly-Correlated Variables)

Alexandr Andoni, Rishabh Dudeja, Daniel Hsu, **Kiran Vodrahalli**

ALT 2019

Learning Sparse Monomials

Sparse high-dim
log-log regression

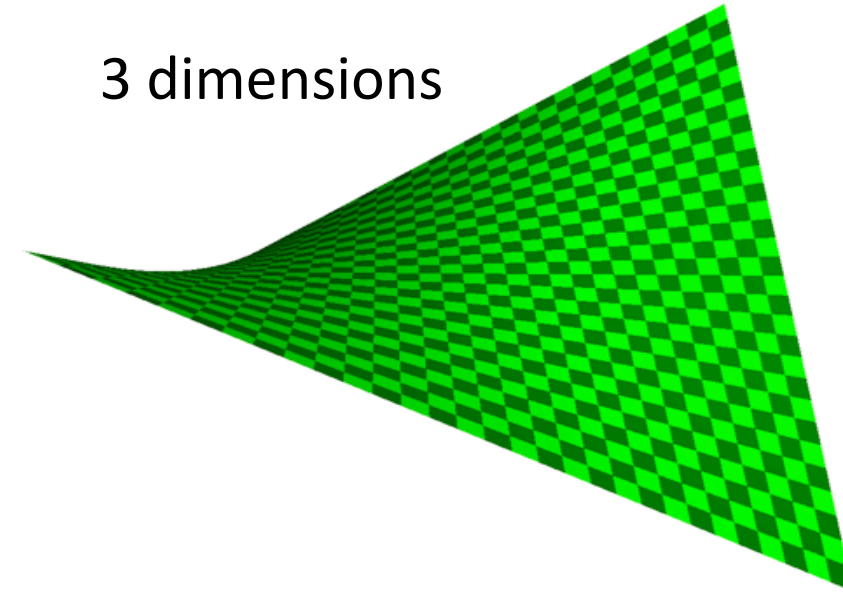


In p dimensions
and k sparse

Ex: $f(x_1, \dots, x_p) := \underbrace{x_3 \cdot x_{17} \cdot x_{44} \cdot x_{79}}_{k=4}$

Learning Sparse Monomials

A Simple
Nonlinear
Function Class



In p dimensions
and k sparse

Ex: $f(x_1, \dots, x_p) := \underbrace{x_3 \cdot x_{17} \cdot x_{44} \cdot x_{79}}_{k=4}$

The Learning Problem

Given: $\left\{ \left(\mathbf{x}^{(i)}, f(\mathbf{x}^{(i)}) \right) \right\}_{i=1}^m$, drawn i.i.d.

Assumption 1: f is a k -sparse monomial function

Assumption 2: $\mathbf{x}^{(i)} \sim \mathcal{N}(\mathbf{0}, \Sigma)$

Goal: Recover f exactly

Attribute-Efficient Learning

- Sample efficiency: $m = \text{poly}(\log(p), k)$
- Runtime efficiency: $\text{poly}(p, k, m)$ ops
- Goal: achieve both!

Motivation

$$x_i \in \{\pm 1\}$$

- Monomials \equiv Parity functions
- No attribute-efficient algs!

[Helmbold+ '92, Blum'98, Klivans&Servedio'06, Kalai+'09, Kocaoglu+'14...]

$$x_i \in \mathbb{R}$$

- Sparse sums of monomials
[Andoni+'14]

For **uncorrelated** features:

$$\mathbb{E}[xx^T] =$$

σ_1^2					
	σ_2^2				
		σ_3^2			
			σ_4^2		
				σ_5^2	
					σ_6^2

Motivation

$$x_i \in \{\pm 1\}$$

- Monomials = Positive functions
- No attribute

Question: What if

$$\mathbb{E}[xx^T] = \begin{matrix} \begin{matrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & & & \\ & & & 1 & & \\ \leq \rho & & & & 1 & \\ & & & & & 1 \end{matrix} \end{matrix} \quad ?$$

$$x_i \in \mathbb{R}$$

regression
[+ '04, Bickel+ '09...]

omials

ated features:

$$\begin{matrix} \sigma_1^2 & & & & & \\ & \sigma_2^2 & & & & \\ & & \sigma_3^2 & & & \\ & & & \sigma_4^2 & & \\ 0 & & & & \sigma_5^2 & \\ & & & & & \sigma_6^2 \end{matrix}$$

Outline for This Project

1. Algorithm
2. Analysis
3. Conclusion

1. Algorithm

The Algorithm

$$\text{Ex: } f(x_1, \dots, x_p) := x_3 \cdot x_{17} \cdot x_{44} \cdot x_{79}$$

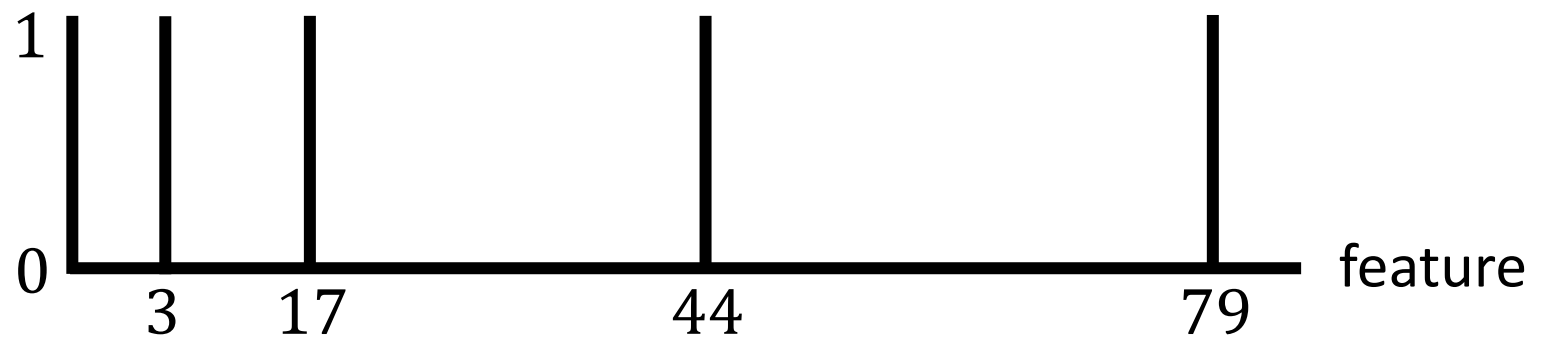
Step 1

$$\left\{ \left(\mathbf{x}^{(i)}, f(\mathbf{x}^{(i)}) \right) \right\}_{i=1}^m \xrightarrow{\log |\cdot|} \left\{ \left(\log |\mathbf{x}^{(i)}|, \log |f(\mathbf{x}^{(i)})| \right) \right\}_{i=1}^m$$

Gaussian Data Log-transformed Data

Step 2

Sparse Regression:
(Ex: Basis Pursuit)



Why is our Algorithm Attribute-Efficient?

- Runtime: basis pursuit is efficient
- **Key Question:** Sample complexity
 - Sparse **linear** regression analysis on transformed vars?
E.g.:

$$\log|f(x_1, \dots, x_p)| := \log|x_3| + \log|x_{17}| + \log|x_{44}| + \log|x_{79}|$$

- **To prove:** sparse linear regression recovery holds

2. Analysis

Restricted Eigenvalue Condition [Bickel, Ritov, & Tsybakov '09]

Restricted Eigenvalue $RE(k)$

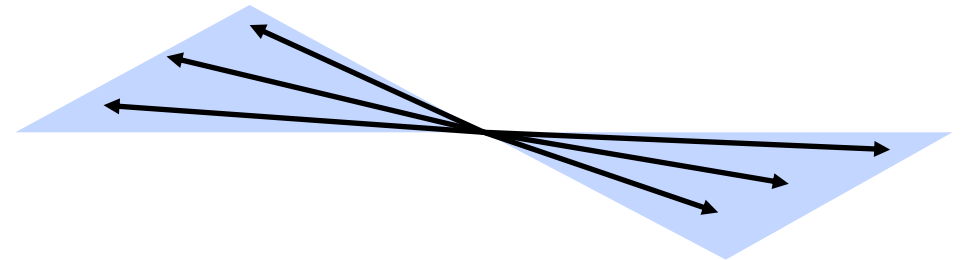
$$\min_{v \in C} \frac{v^T X X^T v}{\|v\|_2^2} > \epsilon$$

“restricted strong convexity”

Note: $RE(k) \geq \lambda_{\min}(X X^T)$

Ex: $S = \{3, 17, 44, 79\}$
 $k = 4$

Cone restriction

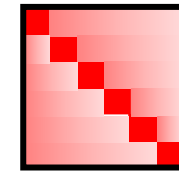


$$C = \{v: \|v_S\|_1 \geq \|v_{S^c}\|_1\}$$

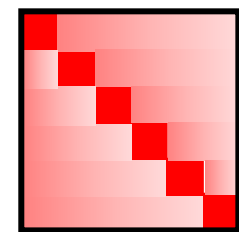
$$|S| = k$$

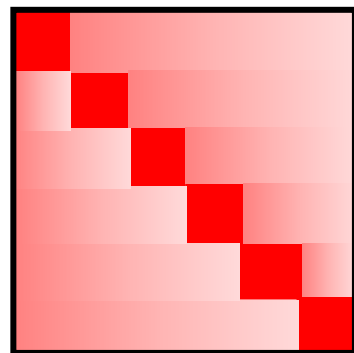
Sufficient to prove exact recovery
for basis pursuit in
sparse linear regression!

Degenerate High Correlation


$$= \mathbb{E}[xx^T]$$

Consider the example:


$$= \begin{bmatrix} 1 & 0 & \sqrt{.5} & & \\ 0 & 1 & \sqrt{.5} & 0 & \\ \sqrt{.5} & \sqrt{.5} & 1 & & \\ & & & \ddots & \\ 0 & & & & 1 & 0 \\ & & & & 0 & 1 \end{bmatrix}$$


$$\begin{bmatrix} -1/2 \\ -1/2 \\ 1/\sqrt{2} \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \mathbf{0}$$

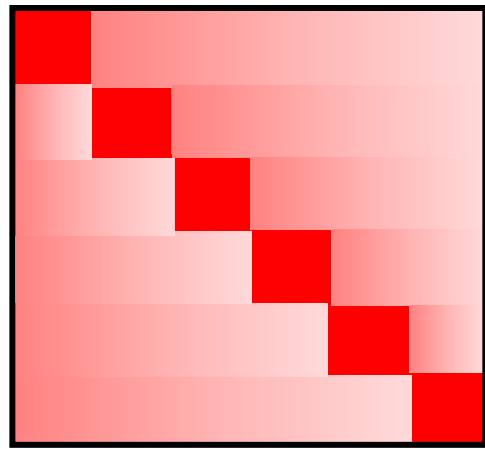
3-sparse

0-eigenvectors can be k -sparse



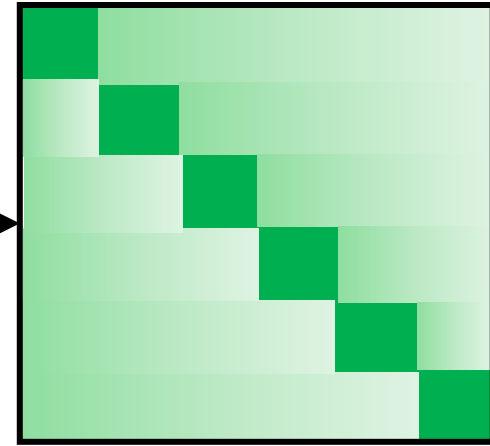
Sparse recovery conditions false!

Log-Transform affects Data Covariance



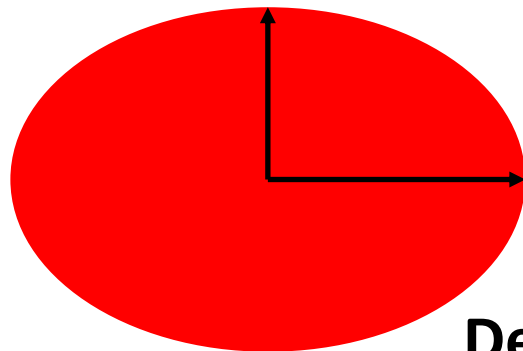
$$\mathbb{E}[xx^T] \succcurlyeq 0$$

$\log |\cdot|$

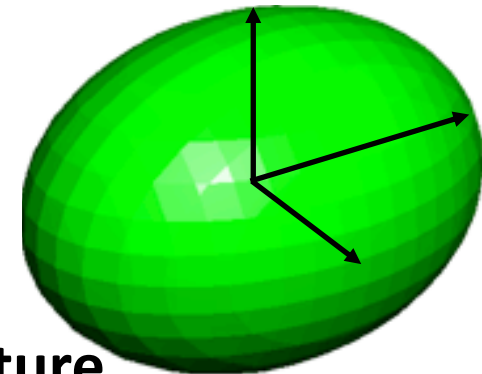


$$\mathbb{E}[\log|x| \log|x|^T] \succ 0$$

Spectral View:



“inflating the balloon”



Destroys correlation structure

$$\begin{bmatrix} \times & & \\ & \times & \\ & & \times \end{bmatrix} = \mathbb{E}[\log|x| \log|x|^T]$$

Sample Complexity Analysis

Population Transformed Eigenvalue

$$\lambda_{\min} \left(\begin{bmatrix} \times & & \\ & \times & \\ & & \times \end{bmatrix} \right) > \epsilon > 0$$

Concentration of Restricted Eigenvalue

$$\left| \lambda_{RE(k)} \left(\begin{bmatrix} \times & & \\ & \times & \\ & & \times \end{bmatrix} \right) - \lambda_{RE(k)} \left(\widehat{\begin{bmatrix} \times & & \\ & \times & \\ & & \times \end{bmatrix}} \right) \right| < \epsilon$$

with probability $\geq 1 - \delta$

$$\lambda_{RE(k)} \left(\widehat{\begin{bmatrix} \times & & \\ & \times & \\ & & \times \end{bmatrix}} \right) > 0$$

with high probability

Exact Recovery for Basis Pursuit
with high probability

$$\begin{bmatrix} \times & \times & \times \\ \times & \times & \times \\ \times & \times & \times \end{bmatrix} = \mathbb{E}[\log|x| \log|x|^T]$$

Sample Complexity Analysis

Population Transformed Eigenvalue

$$\lambda_{\min} \left(\begin{bmatrix} \times & \times & \times \\ \times & \times & \times \\ \times & \times & \times \end{bmatrix} \right) > \epsilon > 0$$

Concentration of Restricted Eigenvalue

$$\left| \lambda_{RE(k)} \left(\begin{bmatrix} \times & \times & \times \\ \times & \times & \times \\ \times & \times & \times \end{bmatrix} \right) - \lambda_{RE(k)} \left(\widehat{\begin{bmatrix} \times & \times & \times \\ \times & \times & \times \\ \times & \times & \times \end{bmatrix}} \right) \right| < \epsilon$$

probability $\geq 1 - \delta$

Sample Complexity Bound:

$$m = O \left(\frac{k^2 \log 2k}{1 - \rho} \cdot \log^2 \frac{2p}{\delta} \right)$$

with high probability

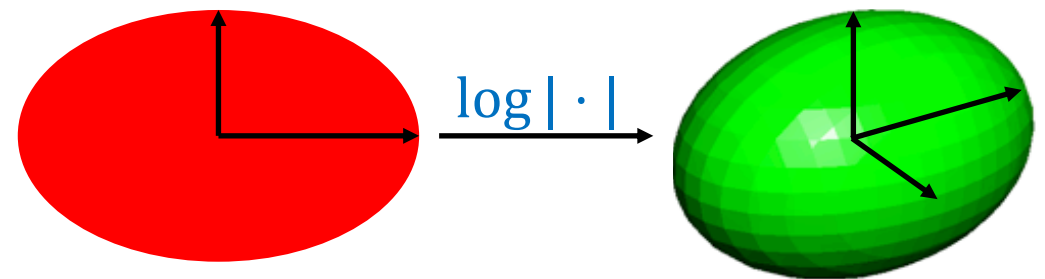


Exact Recovery for Basis Pursuit
with high probability

3. Conclusion

Recap

- Attribute-efficient algorithm for **monomials**
 - Prior (nonlinear) work: **uncorrelated** features
 - This work: allow highly **correlated** features
 - Works beyond multilinear monomials
- Blessing of nonlinearity



Low Rank Deep Learning

Kiran Vodrahalli, Rakesh Shivanna, Mahesh Sathiamoorthy, Sagar Jain, Ed Chi

Google Brain Research Internship (Summer + Fall 2021)

Speeding Up Deep Nets

- Deep neural networks are extremely large today.
- Goal: speed up forward and backward passes
- Example approach: sparse deep networks

Low Rank Deep Models

Replace full-rank layers with low-rank equivalents:

Given weights of layer i :

$$W_i = U_i V_i^T$$

Then replace the standard parameterization w/RHS.

Prior Work [Khodak et. al. 2021]

- Low-rank methods outperform sparse methods if tuned correctly
- Key issues:
 - 1) Initialization of the low-rank parameters
 - 2) Regularization of weights

Impact of Initialization

- Can achieve $\sim 1\%$ additive gain in accuracy by choosing better initialization
- Khodak et al 2021 studies small image classification datasets
- Key approach: **spectral initialization**

Outline for This Project

1. Low-Rank Initialization Scheme

2. Theory

1. Low-Rank Initialization Scheme

Spectral Initialization

For each layer $W \in R^{m \times n} \sim D$:

Minimize the Frobenius distance between the full-rank initialization **parameters** and the low rank parameters:

$$\min_{U \in R^{m \times r}, V \in R^{n \times r}} \|W - UV^T\|_F^2$$

Generalized Spectral Initialization

For each layer $W \in R^{m \times n} \sim D$ with nonlinearity σ :

Perform **distillation**: Minimize ℓ_2^2 error between the **function** outputs of full-rank initialization and low rank initialization:

$$\min_{U \in R^{m \times r}, V \in R^{n \times r}} E_{x \sim N(0, I)} [\|\sigma(Wx) - \sigma(UV^T x)\|_2^2]$$

Generalized Spectral Initialization

For each layer $W \in R^{m \times n} \sim D$ with nonlinearity σ :

Perform **distillation**: Minimize ℓ_2^2 error between the **function** outputs of full-rank initialization and low rank initialization:

Results in empirical gains over spectral initialization!

$$\min_{U \in R^{m \times r}, V \in R^{n \times r}} E_{x \sim N(0, I)} [\|\sigma(Wx) - \sigma(UV^T x)\|_2^2]$$

2. Theory

Is GSpectral Initialization Tractable?

- Suppose $W_{ij} \sim N\left(0, \frac{1}{\sqrt{n}}\right)$ for layer weight $W \in R^{m \times n}$
- Define $f_W(x) := \sigma(Wx)$
- Given $D_W = \{(x, f_W(x)) : x \sim N(0, I_{n \times n})\}$, find \hat{U}, \hat{V} s.t.

$$\mathbb{E}_{x \sim \mathcal{N}(0, I_{n \times n})} \left[\left\| \sigma(\hat{U}\hat{V}^T x) - f_W(x) \right\|_2^2 \right] < \text{OPT} + \epsilon$$

Is GSpectral Initialization Tractable?

For GSpectral algorithm to be efficient:

- Return \hat{U}, \hat{V} w/ $opt + \epsilon$ error w/ prob $\geq \frac{3}{4}$
- $\epsilon = \frac{1}{10}$
- Runtime $\text{poly}(n)$

Related Work

ReLU Regression (additive square loss, learn $\sigma(w^T x)$)

- Realizable case w/Gaussian x : Gradient Descent succeeds
[Soltanolkotabi 2017]
- Agnostic case w/Gaussian x : GD (+ any SQ algorithm) achieving squared loss generalization error $opt + \epsilon$ requires $\exp(\Theta(n^c))$ statistical queries or $n^{\Theta((\frac{1}{\epsilon})^{2b})}$ samples per query for some $b, c \in (0, \frac{1}{2})$. Also the basic problem is SPWN-hard.
[Goel et. al. 2019, 2020]
- Agnostic case w/log-concave x : $O(opt) + \epsilon$ has polytime algo
[Diakonikolas et. al. 2020]

Our Setting

- Combines average-case weights and Gaussian data
- Not realizable, but not arbitrary output distribution
- Common assumptions from theory are practical!

Main Results Teaser

- There is an efficient algorithm for constant rank!
- **Algorithm:**
 1. Exact algorithm in runtime $\text{poly}(n)$ when W is given
 2. Recover W from samples via m realizable ReLU regressions.

Main Results Teaser

- Suppose width is super-linear in dimension.
- High-dimension + Low Rank
 - Then, gap between GSpectral and Spectral grows with dimension.

Future Research Plans

Resource-Efficient Sequence Modeling

- Sequence modeling / time series abound in the sciences and ML
 - Language modeling
 - Brain recordings
 -
- Broadly useful simulation/modeling tool
- Limitation of modern deep sequence models: small context!

Resource-Efficient Sequence Modeling

Key Question 1:

Can we employ techniques from low-rank and sparse modeling to achieve **long-range context** neural sequence models in **sublinear space and time**?

Resource-Efficient Sequence Modeling

Key Question 2:

Can we employ techniques from sketching/streaming theory to analyze **long-range context** neural sequence models in **sublinear space and time**?

For reference

Monomials

Population Minimum Eigenvalue

$$\begin{bmatrix} \blacksquare & & \\ & \blacksquare & \\ & & \ddots \\ & & & \blacksquare \end{bmatrix} = \mathbb{E}[\log|x| \log|x|^T]$$

$$\begin{bmatrix} \blacksquare & & \\ & \blacksquare & \\ & & \ddots \\ & & & \blacksquare \end{bmatrix} = \mathbb{E}[xx^T]$$

- Hermite expansion of $\log|\cdot|$:

$$\begin{bmatrix} \blacksquare & & \\ & \blacksquare & \\ & & \ddots \\ & & & \blacksquare \end{bmatrix} = c_0^2 \mathbf{1}_{p \times p} + \sum_{l=1}^{\infty} c_{2l}^2 \begin{bmatrix} \blacksquare & & \\ & \blacksquare & \\ & & \ddots \\ & & & \blacksquare \end{bmatrix}^{(2l)}$$

- $l \geq 1$: $c_{2l}^2 \sim \frac{\sqrt{\pi}}{4} \cdot \frac{1}{l^{3/2}}$

- $\begin{bmatrix} \blacksquare & & \\ & \blacksquare & \\ & & \ddots \\ & & & \blacksquare \end{bmatrix}^{(2l)}$ off-diagonals decay fast!

- Apply λ_{min} to Hermite formula:

$$\lambda_{min} \begin{bmatrix} \blacksquare & & \\ & \blacksquare & \\ & & \ddots \\ & & & \blacksquare \end{bmatrix} \geq \sum_{l=1}^{\infty} c_{2l}^2 \lambda_{min} \begin{bmatrix} \blacksquare & & \\ & \blacksquare & \\ & & \ddots \\ & & & \blacksquare \end{bmatrix}^{(2l)}$$

- Apply Gershgorin Circle Theorem:

$$\lambda_{min} \begin{bmatrix} \blacksquare & & \\ & \blacksquare & \\ & & \ddots \\ & & & \blacksquare \end{bmatrix}^{(2l)} \geq 1 - (p - 1)\rho^{2l}$$

(for large enough l)

$$\mathbb{E}[\log|x| \log|x|^T]$$

Concentration of Restricted Eigenvalue

- $|\lambda_{RE}(k)(\mathbb{E}[\log|x| \log|x|^T]) - \lambda_{RE}(k)(\widehat{\mathbb{E}[\log|x| \log|x|^T]})| < k \cdot \|\mathbb{E}[\log|x| \log|x|^T] - \widehat{\mathbb{E}[\log|x| \log|x|^T]}\|_\infty$
- Log-transformed variables are **sub-exponential**
- Elementwise ℓ_∞ error concentrates
 - [Kuchibhotla & Chakraborty '18]